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OBSERVATIONS ON THE PERFORMANCE OF AVL TREES

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S. H. Fuller, and E. B. Kaehler

Department of Computer Science
Carnegie-Mellon University
Pittsburgh, Pennsylvania
July, 1973

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ABSTRACT

This paper presents the results of a series of simulations that investigate the performance of AVL trees. It is shown that the only statistic of AVL trees that is a function of the size of the tree is the time to search for an item in the tree; the performance of all other procedures for maintaining AVL trees are independent of the size of the tree for trees greater than \( \sim 30 \) nodes. In particular it was discovered that an average of .465 restructures are required per insertion and .214 restructures per deletion. Moreover, an average of 2.78 nodes are revisited to restore the AVL property on insertion, and 1.91 nodes are revisited on deletion. Actual timings of the AVL procedures for insertion, searching, and deletion are presented to provide a practical guide to estimating the cost of using AVL trees.
INTRODUCTION

This paper empirically examines the computational cost of insertion, deletion, and retrieval in AVL trees. An AVL tree is any rooted, binary tree with every node having the following property:

AVL property. The height of the left subtree differs by at most one from the height of the right subtree. (The height of a tree is the length of the longest path from the root node to a leaf node.)

For example, the tree in Figure 1(a) is an AVL tree but the tree in Figure 1(b) is not because nodes A and D do not exhibit the AVL property. Given that a node possesses the AVL property, we will refer to it as balanced, left heavy, or right heavy depending on whether the height of the left subtree is equal to, greater than, or less than the height of the right subtree.

Immediately after inserting or deleting a node from an AVL tree one or more nodes may lose the AVL property. Figure 2 shows the two cases that can occur on insertion (and the two most common cases for deletion) and how to locally restructure the tree to restore the AVL property to all the nodes. A third case restructuring exists in deletion. It is similar to the single rotation case shown in Figure 2(a) except subtree B has a height of h+1, i.e., node C is balanced. A single rotation is sufficient to restore the AVL property to the critical node and we will subsequently refer to this case as the modified single rotation case. For a more detailed description of AVL trees see [1, 2, 3, 4, 5, 6, 7].
(a) An AVL tree

(b) A non-AVL tree

Figure 1. Search Trees

(a) The single rotation case.

(b) The double rotation case.

Figure 2. The Two Restructuring Cases for Insertion
For a tree structure in which insertion and deletion operations are frequently performed, it is important to know the costs of performing those operations as well as the cost of locating a node in the tree. AVL trees have the attractive property that all three operations (insertion, deletion, and retrieval) can be performed in $O(\log N)$ steps, i.e., on the order of $\log N$ steps, where $N$ is the number of nodes in the tree. This is in contrast to random trees and completely balanced trees in which the worst case of at least one of the three operations can take as many as $O(N)$ steps. Our goals here are to empirically find the average number of comparisons to find a node in the tree and to obtain more detailed estimates of the costs for restructuring the tree after an insertion or deletion.

**EMPIRICAL OBSERVATIONS**

In order to observe the performance of AVL trees, we presented random permutations of an ordered list to the procedure that inserts nodes into the AVL trees. Specifically, we used a uniform random number generator to provide the values of the successive nodes to be inserted. To study the deletion process we selected any node in the tree for deletion with equal probability. To minimize correlation in the simulation we did $N$ insertions and then $N$ deletions, etc. Therefore, all observations of inserting (deleting) a node into an $N$ node tree are independent events.

For the statistics that follow, 500 trees of size 5000 nodes were built up and then broken down, collecting statistics on trees of size 1 to 5000 in the process.

*The random number generator used was:

$$x_{i+1} = 3141592631 \cdot x_i + 14522135347 \mod 2^{35}.$$
On insertion the properties we tabulated were: (1) the average number of comparisons necessary to locate the position where a new node should be added (this is the average depth of the leaves and semi-leaves), (2) the percentage of insertions that caused a restructuring to be performed (statistics were kept for both types of restructuring), and (3) the average number of nodes visited during the traceback procedure (counted from the father of the node just added to the tree to the node at which traceback terminated).

On deletion the properties we tabulated were: (1) the average number of comparisons necessary to locate the node to be deleted (this is the average depth of all nodes in the tree), (2) the probable number of restructurings necessary on each deletion (statistics were kept for each of the three types of restructuring), and (3) the number of nodes visited during the traceback procedure (counted from the father of the node deleted from the tree to the node at which traceback terminated). On deletion, if the node to be deleted was not a leaf or a semi-leaf, we interchanged that node with its predecessor or successor before deleting it.

Table 1 and Figure 3 present the results for insertion and deletion. The graphs for the average number of comparisons on insertion and deletion show that the retrieval time is logarithmic in the number of nodes in the tree. All other statistics, however, when plotted on graphs similar to Figure 3, were observed to be asymptotically independent of the size of the tree and, to within the precision of the simulation, the statistics had reached their asymptotic values for trees greater than ~30 nodes. Our results for the

*The node to be deleted was interchanged with its predecessor or successor depending on whether the node was heavy to the left or right, respectively. If the node was balanced, the node was interchanged with its predecessor.
Table 1. Insertion and Deletion Statistics

<table>
<thead>
<tr>
<th>Insertion:</th>
<th>Mean</th>
<th>Standard Deviation</th>
<th>95% Confidence Interval for Mean</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single Rotation rebalance</td>
<td>.2327</td>
<td>.4226</td>
<td>±.0006</td>
</tr>
<tr>
<td>Double Rotation rebalance</td>
<td>.2324</td>
<td>.4223</td>
<td>±.0006</td>
</tr>
<tr>
<td>Number of nodes visited in traceback</td>
<td>2.778</td>
<td>1.625</td>
<td>±.003</td>
</tr>
</tbody>
</table>

| Deletion:                                      |        |                    |                                 |
| Modified Single Rotation rebalance            | .0536  | .2253              | ±.0003                          |
| Single Rotation rebalances                    | .0781  | .2838              | ±.0004                          |
| Double Rotation rebalances                    | .0826  | .2888              | ±.0004                          |
| Number of nodes visited in traceback          | 1.912  | 1.410              | ±.002                           |
searches on insertion
(approx. $1.013 \log_2 N + .104$)

searches on deletion
(approx. $1.003 \log_2 N - .798$)

Figure 3. Expected Number of Comparisons to Locate an Item in an AVL tree of N Nodes. (Each point is surrounded by its 95% confidence interval.)
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searches on insertion
(approx. $1.013 \log_2 N + .104$)

searches on deletion
(approx. $1.003 \log_2 N - .798$)
insertion costs concur with those of others [4]. The most surprising re-
sults are those for deletion; the worst case restructuring might involve
log N rebalances, but we observed that the probable number of rebalances
per deletion was half that expected for insertion. A related observation
is that the traceback on deletion visited approximately one less node per
operation than on insertion.

It is interesting to note on insertion, to within the 95% confidence
intervals of the simulation, that the single and double rotation cases appear
to occur with equal frequency. In fact, a simple argument shows they must
be equally probable. In Figure 2(a) consider the subtree rooted at C: it
includes all items in the interval bounded by the values of nodes A and X.
Since we require the nodes in the entire tree to arrive in random order, all
the nodes that are within the interval bounded by A and X must also arrive
in random order. Hence the subtree rooted at C is an AVL tree that is as
probable to be left heavy as right heavy. However, the single feature that
distinguishes the single rotation case from the double rotation case is
whether or not node C is heavy in the same, or opposite, direction as the
critical node.
TIMING STATISTICS

To compare the actual costs involved in performing the retrieval and restructuring operations, we gathered timing statistics for the operations. The following cost functions were derived from an implementation of the AVL procedures written in BLISS/10 [7] and run on a PDP-10 (all times are in microseconds):

**Insertion**

<table>
<thead>
<tr>
<th>Operation</th>
<th>Cost</th>
</tr>
</thead>
<tbody>
<tr>
<td>search for the location to attach the new node</td>
<td>150 + 90 per compare*</td>
</tr>
<tr>
<td>attach node to the tree</td>
<td>80</td>
</tr>
<tr>
<td>restructure the tree</td>
<td>350</td>
</tr>
<tr>
<td>total</td>
<td>580 + 90 log₂ N</td>
</tr>
</tbody>
</table>

**Deletion**

<table>
<thead>
<tr>
<th>Operation</th>
<th>Cost</th>
</tr>
</thead>
<tbody>
<tr>
<td>search for the node to be deleted</td>
<td>150 + 90 per compare*</td>
</tr>
<tr>
<td>detach the node from the tree</td>
<td>325</td>
</tr>
<tr>
<td>restructure the tree</td>
<td>250</td>
</tr>
<tr>
<td>total</td>
<td>725 + 90 log₂ N</td>
</tr>
</tbody>
</table>

These results show that deletion is slightly more expensive than insertion, but that for large trees, the search time is the dominant factor in both operations.

*Figure 3 gives the expected number of comparisons as a function of the size of the tree.*
References


APPENDIX: A Set of Procedures for Inserting into, Deleting from, and Searching AVL Trees

integer array tree[0:n,1:6],drct,path[0:2.25*ln(n+2)];
integer treebase,level;

comment These identifiers represent the data structures to be used in the procedures.
1) tree represents the AVL tree, it is accessed with two values, a pointer to a node and a field specification within that node. tree is declared as an array, but any data structure accessed in the above manner is acceptable. The actual tree constructed is built as the left subtree of a special header node pointed to by treebase.
2) path and drct are used as a stack to record movements through the tree. path holds pointers to nodes and drct holds the direction moved when stepping down from the node identified by the corresponding pointer in path. level is used as a stack pointer into path and drct.

integer nullink,maxkey;
integer llink,rlink,rank,key,infoptr,balance;

comment The first two identifiers above represent constants and the second six represent the field specifiers for each node in the tree. In this implementation, the latter six take on the values 1,...,6 respectively, corresponding to the second index of the array tree.
1) The llink and rlink of each node contain pointers to its left and right sons. The value nullink (which must be chosen to be distinct from all valid link values) in a field indicates that no son is present on that side of the node. llink in the header node holds a pointer to the root node of the tree, rlink in the header always has the value nullink.
2) The rank of each node specifies the relative position of that node in the subtree of which it is the root, i.e., one plus the number of nodes in its left subtree. The rank of the header node, therefore, specifies one plus the number of nodes in the tree.
3) If the AVL tree is being used to store nodes by value, then the key of each node contains the value that uniquely identifies the node and the nodes are stored in lexicographic order based on the value of key. If the AVL tree is being used to store a linear list, then the key values are not necessarily distinct. In this case, each node is accessed by specifying its position in the postorder sequence of the tree. The key of the header node contains the value maxkey which must be chosen larger than any key to be added to the tree.
4) the infoptr of each node contains a pointer to the information associated with that node. If only a small, constant amount of information is associated with each node, the pointer can be eliminated and be replaced by the information itself. The infoptr of the header node always has the value nullink.

5) the balance of each node indicates the balance of the subtree for which that node is the root. The possible values are: left heavy, right heavy, or balanced. The balance of the header node is undefined.

```
integer balanced, left, right, found, notfound, bounderror, delete, retrieve, insert;

comment These identifiers represent constants in the procedures. They may be assigned any value such that within each of the following three sets, each member has a distinct value.
{(balanced, left, right)}
{(found, notfound, bounderror)}
{(delete, retrieve, insert)}

integer procedure OPPSIDE(side);
integer side; value side;
OPPSIDE:=if side = left then right else left;

integer procedure OPPSLINK(side);
integer side; value side;
OPPSLINK:=if side = left then rlink else llink;

integer procedure SIDELINK(side);
integer side; value side;
SIDELINK:=if side = left then llink else rlink;

procedure INITHEADER;
begin
comment
Function: to initialize the special header node for the tree. This procedure must be called before any tree operations are performed.

Side effects: None.

  tree[treerbase, rank] := 1;
  tree[treerbase, key] := maxkey;
  tree[treerbase, infoptr] := nullink;
  tree[treerbase, balance] := balanced
end INITHEADER;
```
integer procedure SEARCH(positionsearch, searchkey, typesearch);
boolean positionsearch; integer searchkey, typesearch;
value positionsearch, searchkey, typesearch;
begin integer tpoint, field, loopdummy, chgval;
comment
Permissible values for the parameters:
  1) positionsearch - true, false
  2) searchkey - a list position or a key value
  3) type search - insert, retrieve, delete

Function: to search for a node in the tree. If positionsearch = true, then searchkey is interpreted as a position in the postorder sequence of the tree, otherwise searchkey is interpreted as a key value.

Side effects:
  1) path and drct are filled with the links and directions taken on the path from the header node to the desired node. path[level] points to the desired node when it is found in the tree, otherwise it points to the leaf or semi-leaf from which the desired node could be a son. On insertion drct[level] specifies which side of the node pointed to by path[level] the new node will be added.
  2) type search indicates the purpose of the search, i.e., a search for a position to insert a new node, or a search to find a node so that it may be deleted, or a search for retrieval of information.
  The rank field of the nodes on the path are adjusted for the insert and delete cases with the assumption that the operation will subsequently be performed.

Value of SEARCH:
  1) found - node located in tree, pointed to by path[level].
  2) not found - node not located in tree, path[level] points to node which could be the father of desired node.
  3) bound error - position specified does not occur in list (on search by position only). ;
procedure RESETRANK(typesearch);
integer typesearch; value typesearch;
begin integer chgval, tlevel;
comment
Permissible values for the parameter typesearch: insert, delete.

Function: to restore the value of the rank field in each node. This only has to be done if an attempt was made to insert(by value) a node which already existed in the tree or an attempt was made to delete a node which did not exist in the tree. typesearch specifies for which case the correction is being made(insert, delete).

Side effects: None.

\[ chgval := \text{if } \text{typesearch} = \text{insert} \text{ then } -1 \text{ else } 1; \]
\[ \text{for } \text{level} := (\text{if } \text{chgsw} = \text{insert} \text{ then } \text{level} - 1 \text{ else } \text{level}) \]
\[ \text{step } -1 \text{ until } 0 \text{ do} \]
\[ \text{if } \text{drcx}[\text{level}] = \text{left} \]
\[ \text{then } \text{tree[} \text{path[} \text{level}]\text{rank}] := \]
\[ \text{tree[} \text{path[} \text{level}]\text{rank}] + chgval \]
end RESETRANK;

comment The body of SEARCH begins here. ;
if (positionsearch ∧
((searchkey ≤ 0) ∨
(searchkey > tree[treebase,rank]) ∨
((typesearch ≠ insert ∧ searchkey = tree[treebase,rank])) ∨
(¬ positionsearch ∧ searchkey ≥ maxkey))
then
begin
SEARCH := bounderror;
goto endsrch
end;
ptpoint := treebase;
level := 0;
chgval := \text{if } \text{typesearch} = \text{insert} \text{ then } 1 \text{ else } (\text{if } \text{typesearch} = \text{delete} \text{ then } -1 \text{ else } 0);
field := \text{if } \text{positionsearch} \text{ then } \text{rank} \text{ else } \text{key};
for loop dummy := 1 while true do
begin
path[level] := tpoint;
if searchkey ≠ tree[tpoint, field]
then
begin integer side;
drect[level] := side := if searchkey < tree[tpoint, field]
then left else right;
if position search ∧ (side = right)
then searchkey := searchkey – tree[tpoint, rank];
tree[tpoint, rank] := tree[tpoint, rank] +
(if side = left then chgval else 0);
tpoint := tree[tpoint, SIDE LINK(side)];
if (~ position search) ∧ (tpoint = null link)
then
begin
if typesearch = delete then RESET RANK(delete);
SEARCH := not found;
goto endsrch
end;
level := level + 1
end
else
begin
if typesearch = insert
then
begin
if ~ position search
then RESET RANK(insert)
else
begin
drect[level] := left;
tree[path[level], rank] :=
tree[path[level], rank] + 1;
if tree[path[level], link] ≠ null link
then
begin
level := level + 1;
path[level] :=
   tree[path[level - 1], link];
drect[level] := right;
for path[level + 1] :=
   tree[path[level], rlink]
   while (path[level + 1] ≠ null link) do
begin
   level := level + 1;
   drect[level] := right
end
end
end;
SEARCH := found;
goto endsrch
end
end
endsrch:
end SEARCH;
procedure SINGLEROTATE;
begin
  integer pfather,pcritical,peritson1,side;
  comment
  Function: to perform a 'single' rotation at a critical node to re-establish the AVL property. The llink, rlink, balance, and rank values are adjusted for the critical node, its father and the the heavy side son of the critical node.
  Side effects: none.
  
  pfather:=path[level-1];
  peritical:=path[level];
  peritson1:=path[level+1];
  side:=tree[peritical,balance];
  tree[pfather,SLDELINK(drct[level-1])]:=peritson1;
  tree[peritical,SLDELINK(side)]:=
    tree[peritson1,OPPSLINK(side)];
  tree[peritson1,OPPSLINK(side)]:=peritical;
  tree[peritical,rank]:=
    tree[peritical,rank]-
    (if side = left then tree[peritson1,rank] else 0);
  tree[peritson1,rank]:=
    tree[peritson1,rank]+
    (if side = right then tree[peritical,rank] else 0);
  tree[peritical,balance]:=tree[peritson1,balance]:=balanced
end SINGLEROTATE;
procedure DOUBLE ROTATE;
begin integer pfather, pcritical, pcritson1, pcritson2, side;
comment
Function: to perform a 'double' rotation at a critical node
to re-establish the AVL property. The link, rlink,
balance, and rank values are adjusted for the critical
node, its father, the the heavy side son of the
critical node, and the heavy side son of that son.

Side effects: none.

pfather := path[level-1];
pcritical := path[level];
pcritson1 := path[level+1];
pcritson2 := path[level+2];
side := tree[pcritical,balance];
tree[pfather, SIDELINK(drcet[level-1])] := pcritson2;
tree[pcritson1,OPPSLINK(side)] :=
   tree[pcritson2, SIDELINK(side)];
tree[pcritical, SIDELINK(side)] :=
   tree[pcritson2, OPPSLINK(side)];
tree[pcritson2, SIDELINK(side)] := pcritson1;
tree[pcritson2, OPPSLINK(side)] := pcritical;
tree[pcritical, rank] :=
   if side = left
     then tree[pcritson1, rank] + tree[pcritson2, rank] else 0;
tree[pcritson1, rank] :=
   tree[pcritson1, rank] -
   if side = right then tree[pcritson2, rank] else 0;
tree[pcritson2, rank] :=
   tree[pcritson2, rank] +
   if side = left then tree[pcritson1, rank] else tree[pcritical, rank];
tree[pcritical, balance] :=
   if tree[pcritson2, balance] = side
     then OPPSIDE(side) else balanced;
tree[pcritson1, balance] :=
   if tree[pcritson2, balance] = OPPSIDE(side)
     then side else balanced;
tree[pcritson2, balance] := balanced
end DOUBLE ROTATE;
procedure ATTACHNODE(pfree,newkey,newinfoptr);
  integer pfree,newkey,newinfoptr;
  value pfree,newkey,newinfoptr;
begin
  comment
  Permissible values for the parameters:
  1) pfree - a pointer to any empty node
  2) newkey - value of key for the new node
  3) newinfoptr - value of information pointer for the new node

  Function: to insert a new node into the tree.
  The new node is attached to the node pointed to by path[level]
on the side specified by drct[level].

  Side effects: pfree is placed in path[level+1] for use by the rotation procedures.

  tree[path[level],SIDELINK(drct[level])]:=pfree;
  tree[pfree,rank]:=1;
  tree[pfree,lkink]:=tree[pree,link]:=nullink;
  tree[pfree,balance]:=balanced;
  tree[pfree,key]:=newkey;
  tree[pfree,infoptr]:=newinfoptr;
  path[level+1]:=pfree
end ATTACHNODE;
procedure REBUILDINSERT;
begnin
comment
Function: to trace back along the path from the father of the node just attached to the tree, checking that the AVL property has been maintained. A rotation is performed if the property no longer holds at a node. At most one rotation is performed but traceback may terminate without performing a rotation or reaching the top of the tree.

Side effects: none. ;

tree[path[level],balance]:=
    if tree[path[level],balance] = balanced
        then dret[level] else balanced;
    if tree[path[level],balance] ≠ balanced
        then
            begin integer loopdummy; boolean critsw;
                critsw:=false;
                for loopdummy:=1 while (level > 1) do
                begin
                    level:=level-1;
                    if tree[path[level],balance] ≠ balanced
                        then
                            begin
                                tree[path[level],balance]:= 
                                    if tree[path[level],balance] = dret[level]
                                        then dret[level] else balanced;
                                critsw:=
                                    if tree[path[level],balance] = dret[level]
                                        then true else false;
                                goto chkcrit
                            end
                        else
                            goto chkcrit
                    end
            end
      else tree[path[level],balance]:=dret[level]
end:
chkcrit:
    if critsw
        then
            begin
                if tree[path[level],balance] =
                    tree[path[level+1],balance]
                    then SINGLEROTATE
                    else DOUBLEROTATE
            end
end
end REBUILDINSERT;
procedure DETACHNODE;
begin
  integer pdel;
  comment
  Function: to delete the node specified by path[level] from the tree.

  Side effects: If the node to be deleted is not a leaf or a semi-leaf, then the node is interchanged with its postorder predecessor(successor) before being deleted. path and drct are filled out with the path down to the predecessor(successor). The predecessor is chosen if the node is left heavy or balanced, otherwise the successor is chosen.

  pdel:=path[level];
  if (tree[pdel, llink] ≠ nullink) ∧
    (tree[pdel, rlink] ≠ nullink)
  then
    begin
      integer tpoint, sllevel, temp, side, chgval, slink;
      comment Node is not a leaf or semi-leaf, find its predecessor(successor).
      sllevel:=level-1;
      drct[level]:=side:=if tree[pdel, balance] = right
        then right else left;
      chgval:=if side = left then 0 else 1;
      tree[pdel, rank]:=
        tree[pdel, rank]-(1-chgval);
      level:=level+1;
      path[level]:=tree[pdel, SIDELINK(side)];
      side:=OPPSIDE(side);
      slink:=SIDEINK(side);
      for path[level+1]:=tree[path[level], slink]
        while (path[level+1] ≠ nullink) do
          begin
            drct[level]:=side;
            tree[path[level], rank]:=
              tree[path[level], rank]-chgval;
            level:=level+1
          end;
      comment Perform interchange.
      tpoint:=path[level];
      tree[path[sllevel], SIDEINK(drct[sllevel])]:=tpoint;
      temp:=tree[pdel, llink];
      tree[pdel, llink]:=tree[tpoint, llink];
      tree[tpoint, llink]:=temp;
      temp:=tree[pdel, rlink];
      tree[pdel, rlink]:=tree[tpoint, rlink];
      tree[tpoint, rlink]:=temp;
      tree[tpoint, rank]:=tree[pdel, rank];
      tree[tpoint, balance]:=tree[pdel, balance];
      path[sllevel+1]:=tpoint
    end;
  comment Delete leaf or semi-leaf.
  tree[path[level-1], SIDEINK(drct[level-1])]:=
    tree[pdel, llink] tree[pdel, llink] = nullink
    then rlink else llink
end DETACHNODE;
procedure REBUILDDELETE;
begin integer loopdummy;
comment
Function: to trace back along the path from the father of the node deleted from the tree, checking that the AVL property has been maintained. A rotation is performed if the property no longer holds at a node. Several rotations may be necessary but traceback may terminate without performing a rotation or reaching the top of the tree.

Side effects: none.

for loopdummy:=1 while (level > 1) do
begin
level:=level-1;
if tree[path[level],balance] =balanced then
begin
  tree[path[level],balance]:=OPPSIDE(drc[level]);
goto endrbld
end
else if tree[path[level],balance] = drc[level] then
  tree[path[level],balance]:=balanced
else
  begin
    path[level+1]:=tree[path[level],OPPSLINK(drc[level])];
    if tree[path[level+1],balance] = balanced then
      begin
        SINGLEROTATE;
        tree[path[level],balance]:=OPPSIDE(drc[level]);
        tree[path[level+1],balance]:=drc[level];
goto endrbld
      end
    else if tree[path[level],balance] =
          tree[path[level+1],balance] then SINGLEROTATE
    else
      begin
        path[level+2]:=tree[path[level+1],
                             SIDEILINK(tree[path[level+1],
                                              balance)];
        DOUBLEROTATE
      end
  end
end;
endrbld:
end REBUILDDELETE;